

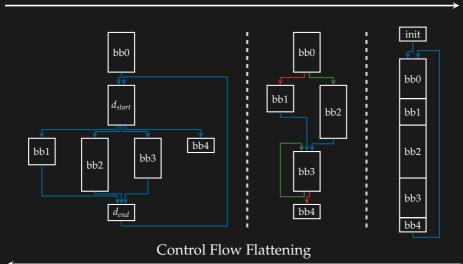


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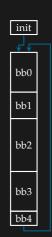
#### Control Flow Linearization



- ► x86(-64) is Turing complete.
- Question: Smallest subset of x86(-64) instructions that still is Turing complete?



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- Question: Smallest subset of x86(-64) instructions that still is Turing complete?
- ► Answer: 1 instruction mov [1]
- $\Rightarrow$  The M/o/Vfuscator: C to x86/mov compiler [2]
- ⇒ Control flow Linearization by instruction substitution
- [1] Mov Is Turing Complete. Stephen Dolan. 2013.
- [2] The M/o/Vfuscator: Turning the mov Instruction into a Soul-Crushing RE Nightmare. Christopher Domas. 2015.



```
eax, dword 83F55B8
mov
mov
        dword_81F5440, eax
mov
        dword_81F5444, edx
mov
mov
mov
mov
mov
        al, byte ptr dword_81F5440
        ecx, off_804FA50[eax*4]
mov
        dl, byte ptr dword_81F5444
mov
mov
        dword_81F5430, edx
mov
        al, byte ptr dword_81F5440+1
mov
        ecx, off 804FA50[eax*4]
mov
        dl, byte ptr dword_81F5444+1
mov
        dl, [ecx+edx]
mov
        dword 81F5434, edx
mov
        eax, dword_81F5430
mov
        edx, dword 81F5434
mov
        eax, off_804C4F0[eax*4]
mov
mov
mov
        dword 81F5430, eax
mov
        eax, off 804C4F0[eax*4]
mov
        dword_81F5430, eax
mov
```

#### Motivation

CFL Hindering Program Analysis



Effectiveness against the angr (🗐) symbolic execution engine:

Firmalice [3]:	Clean	Obfuscated    Bid   Bid
# Basic Blocks Executed	37	99,999
Analysis Time (s)	5.1	1704.3
Explored Paths	2	1
Executable Size (bytes)	5400	5,962,776



[3] Firmalice – Automatic Detection of Authentication Bypass Vulnerabilities in Binary Firmware. Yan Shoshitaishvili et al. . 2015

#### Motivation

CFL Hindering Program Analysis



Effectiveness against the angr ( $\mathfrak{S}$ ) symbolic execution engine:

Firmalice [3]:	Clean	Obfuscated
	bb1 bb2 bb5	bb0 bb0 bb2 bb5 bb4
# Basic Blocks Executed	37	99,999
Analysis Time (s)	5.1	1704.3
Explored Paths	2	1
Executable Size (bytes)	5400	5,962,776



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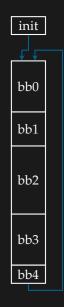


- 1. Find **critical data structures** indicating the linearized program's execution state.
- 2. Infer basic block labels using backward taint analysis and constraint solving.
- 3. Find and identify types of **control flow** changing instructions.
- 4. **Patch** binary to reconstruct control flow.

A Bird's Eye Perspective

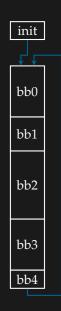


```
1 #define DEFVAR(TYPE, NAME)
TYPE NAME[2] = { 0 }
2 #define TRUVAL(X) (X[1])
3 #define ASSIGN(VAR, VAL, CONDVAR, CONDNUM) \
    do { VAR[TRUVAL(CONDVAR) == CONDNUM] = VAL; } while (0)
6 void nop(void) { return; }
8 int main(int argc, char **argv) {
      DEFVAR(size_t, state); DEFVAR(size_t, cmp);
      DEFVAR(uint64_t, fac);
      DEFVAR(size_t, i); DEFVAR(size_t, j);
      void (*my_exit[2])(int)
                                             = { nop, exit }:
      int (*my_printf[2])(const char *, ...) = { nop, printf };
      do {
         ASSIGN(i, 1,
                                           state, 0);
         ASSIGN(j, atoi(argv[1]),
                                           state, 0);
         ASSIGN(fac, 1,
                                            state, 0);
         ASSIGN(state, 1,
                                               state, 0);
         ASSIGN(fac, TRUVAL(fac) * TRUVAL(i), state, 1);
         ASSIGN(i, TRUVAL(i) + 1, state, 1);
         ASSIGN(cmp, TRUVAL(i) > TRUVAL(j), state, 1);
         ASSIGN(state, 2,
                                              cmp, 1);
         my printf[TRUVAL(state) == 2]("%llu\n", TRUVAL(fac));
         my_exit[TRUVAL(state) == 2](0);
      } while (1);
27 }
```





```
1 #define DEFVAR(TYPE, NAME)
                                 TYPE NAME[2] = \{0\}
2 #define TRUVAL(X) (X[1])
3 #define ASSIGN(VAR, VAL, CONDVAR, CONDNUM) \
    do { VAR[TRUVAL(CONDVAR) == CONDNUM] = VAL; } while (0)
6 void nop(void) { return; }
8 int main(int argc, char **argv) {
      DEFVAR(size t, state); DEFVAR(size t, cmp);
      DEFVAR(uint64 t, fac);
      DEFVAR(size_t, i); DEFVAR(size_t, j);
      void (*my_exit[2])(int)
                                              = { nop, exit };
      int (*my_printf[2])(const char *, ...) = { nop, printf };
     do {
          ASSIGN(i,
                                                state, 0);
                       atoi(argv[1]),
         ASSIGN(j,
                                               state, 0);
          ASSIGN(fac,
                                               state, 0);
          ASSIGN(state, 1,
                                                state, 0);
         ASSIGN(fac, TRUVAL(fac) * TRUVAL(i), state, 1);
          ASSIGN(i, TRUVAL(i) + 1, state, 1);
         ASSIGN(cmp, TRUVAL(i) > TRUVAL(j), state, 1);
         ASSIGN(state, 2,
                                                cmp, 1);
          my printf[TRUVAL(state) == 2]("%llu\n", TRUVAL(fac));
          my_exit[TRUVAL(state) == 2](0);
      } while (1):
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```
1 #define DEFVAR(TYPE, NAME)
                                TYPE NAME[2] = \{0\}
2 #define TRUVAL(X) (X[1])
3 #define ASSIGN(VAR, VAL, CONDVAR, CONDNUM) \
    do { VAR[TRUVAL(CONDVAR) == CONDNUM] = VAL; } while (0)
6 void nop(void) { return; }
8 int main(int argc, char **argv) {
      DEFVAR(size_t, state); DEFVAR(size_t, cmp);
      DEFVAR(uint64 t, fac);
      DEFVAR(size_t, i); DEFVAR(size_t, j);
      void (*my_exit[2])(int)
                                             = { nop, exit }:
      int (*my printf[2])(const char *, ...) = { nop, printf };
     do {
         ASSIGN(i,
                                               state, 0);
                       atoi(argv[1]),
         ASSIGN(j,
                                               state, 0);
         ASSIGN(fac,
                                               state, 0);
         ASSIGN(state, 1,
                                               state, 0);
         ASSIGN(fac, TRUVAL(fac) * TRUVAL(i), state, 1);
         ASSIGN(i, TRUVAL(i) + 1, state, 1);
         ASSIGN(cmp, TRUVAL(i) > TRUVAL(j), state, 1);
         ASSIGN(state, 2,
                                     cmp, 1);
         my_printf[TRUVAL(state) == 2]("%llu\n", TRUVAL(fac));
         my_exit[TRUVAL(state) == 2](0);
      } while (1);
27 }
```



```
1 #define DEFVAR(TYPE, NAME)
                                TYPE NAME[2] = \{0\}
2 #define TRUVAL(X) (X[1])
3 #define ASSIGN(VAR, VAL, CONDVAR, CONDNUM) \
    do { VAR[TRUVAL(CONDVAR) == CONDNUM] = VAL; } while (0)
6 void nop(void) { return; }
8 int main(int argc, char **argv) {
      DEFVAR(size_t, state); DEFVAR(size_t, cmp);
      DEFVAR(uint64 t, fac);
      DEFVAR(size_t, i); DEFVAR(size_t, j);
      void (*my_exit[2])(int)
                                             = { nop, exit };
      int (*my_printf[2])(const char *, ...)
                                             = { nop, printf };
      do {
         ASSIGN(i,
                                               state, 0);
         ASSIGN(j,
                       atoi(argv[1]),
                                               state, 0);
         ASSIGN(fac,
                                               state, 0);
         ASSIGN(state, 1,
                                               state, 0);
         ASSIGN(fac, TRUVAL(fac) * TRUVAL(i), state, 1);
         ASSIGN(i,
                      TRUVAL(i) + 1,
                                               state, 1);
         ASSIGN(cmp, TRUVAL(i) > TRUVAL(j), state, 1);
         ASSIGN(state, 2,
                                          cmp, 1):
         my printf[TRUVAL(state) == 2]("%llu\n", TRUVAL(fac));
         my_exit[TRUVAL(state) == 2](0);
      } while (1);
27 }
```



Example: Program with Linearized Control Flow

• Shortcut: Check state **only once** per basic block, store result in variable ON, set on to false **after each** basic block:

```
1 #define DEFVAR(TYPE, NAME)
TYPE NAME[2] = { 0 }
2 #define TRUVAL(X) (X[1])
3 #define ASSIGN(VAR, VAL, CVAR, CNUM) do { VAR[TRUVAL(CVAR) == CNUM] = VAL; } while (0)
4 #define ASSIGN_FAST(VAR, VAL, ON) do { VAR[TRUVAL(ON)] = VAL; } while (0)
6 int main(int argc, char **argv) {
      DEFVAR(size t, state); DEFVAR(uint64 t, fac); DEFVAR(uint8 t, on);
      DEFVAR(size_t, i); DEFVAR(size_t, j);
      do {
          ASSIGN
                     (on,
                             1,
                                                      state, 0);
          ASSIGN FAST(i,
                                                      on):
                            atoi(argv[1]),
          ASSIGN_FAST(j,
                                                      on);
          ASSIGN FAST(fac,
                                                      on);
          ASSIGN FAST(state, 1,
                                                      on);
          TRUVAL(on) = 0;
          ASSIGN
                     (on,
                                                      state, 1);
          ASSIGN FAST(fac,
                            TRUVAL(fac) * TRUVAL(i), on);
      } while (1);
21 }
```

Finding Critical Data Structures



⇒ Observation: ON becomes the most accessed data structure in linearized code:

```
do {
          ASSIGN
                     (on.
                                                       state, 0);
          ASSIGN_FAST(i,
                                                       on):
          ASSIGN FAST(j,
                             atoi(argv[1]),
          ASSIGN FAST(fac,
                                                       on);
          ASSIGN_FAST(state, 1,
                                                       on);
          TRUVAL(on) = 0;
          ASSIGN
                     (on.
                                                       state, 1);
          ASSIGN FAST(fac,
                             TRUVAL(fac) * TRUVAL(i), on);
      } while (1);
12 }
```

⇒ ON **trivial to detect** by linear sweep disassembly or **frequency analysis** of memory access patterns

A Bird's Eye Perspective

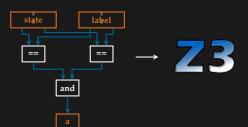
- 1. Find critical data structures indicating the linearized program's execution state.  $\sqrt{\phantom{a}}$
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Inferring Basic Block Labels

• Observation: Any given basic block writes 1 to ON if the state variable equals the respective block's LABEL:

- ⇒ Reconstruct predicate used to access ON (i.e. a = state == 0 in on[a] = 1) using backwards taint analysis.
- ⇒ Build up **syntax tree** of arithmetic / logic operations applied to the state variable.
- $\Rightarrow$  Constrain formula to be 1, and solve system using an **SMT solver** (z3).
- ⇒ Result: List of basic block labels + location of state





A Bird's Eye Perspective

- 1. Find critical data structures indicating the linearized program's execution state.  $\sqrt{\phantom{a}}$
- 2. Infer basic block **labels** using backward taint analysis and constraint solving.  $\checkmark$
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Identifying Types of Control Flow Changing Instructions

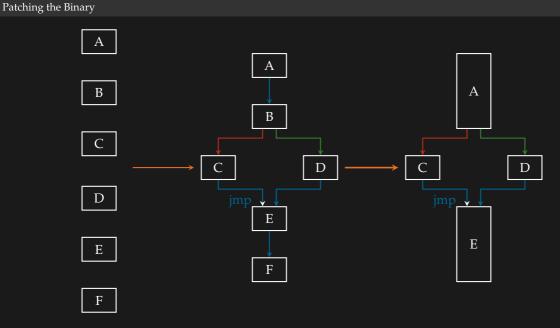
- Employ backwards taint analysis on positions writing to state.
- Four different cases for predicate and value written:



A Bird's Eye Perspective

- 1. Find critical data structures indicating the linearized program's execution state.  $\sqrt{\phantom{a}}$
- 2. Infer basic block labels using backward taint analysis and constraint solving.
- 3. Find and identify types of **control flow** changing instructions. ✓
- 4. **Patch** binary to reconstruct control flow.

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Patching the Binary

- 1. Find critical data structures indicating the linearized program's execution state. ✓
- 2. Infer basic block **labels** using backward taint analysis and constraint solving. ✓
- 3. Find and identify types of **control flow** changing instructions. ✓
- 4. Patch binary to reconstruct control flow. ✓



CFL overhead in terms of run-time (seconds) and code size (bytes):

	Primes		Factorial		SHA-256	
	Non-Lin.	Lin.	Non-Lin.	Lin.	Non-Lin.	Lin.
Non-Sub.	0.88 s	5.03 s	< 0.01 s	< 0.01 s	0.02 s	0.4 s
Non-Sub.	240 B	928 B	1884 B	1936 B	5672 B	8564 B
Sub.	62.82 s	289.47 s	< 0.01 s	< 0.01 s	8.09 s	60.57 s
Sub.	16,957 B	16,957 B	10,684 B	10,684 B	213,740 B	213,740 B

**Deobfuscation times** of the implementation of our algorithm:

Primes	Factorial	SHA-256	AES
0.47 s	0.213 s	0.824 s	3.68 s

#### Evaluation





**Execution time** of the **angr** ( ) symbolic execution engine to **detect** a backdoor in an example executable:

	Clean	Obfuscated	Deobfuscated
# Basic Blocks Executed	37	99,999	87
Execution Time (s)	5.1	1704.3	17.9
Explored Paths	2	1	3
Executable Size (bytes)	5400	5,962,776	5,962,776

#### Conclusion



- Control Flow Linearization unsuited for obfuscating real time applications
- Major challenge for state of the art symbolic execution engines
- Presence of control data structures makes deobfuscation easy

#### Contact



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Sources available - documentation pending:-)
 → Source code:
 https://github.com/kirschju/demovfuscator
 → Project website:
 https://kirschju.re/demov
 → Combating Control Flow Linearization:
 https://kirschju.re/static/cfl.pdf
 → Slides:
 https://kirschju.re/static/ifip.pdf

#### Thanks!